

A kind of two-way smart actuator device based on shape memory polymer and rubber Haiyang DU¹*

Address1: ¹School of Civil Engineering, Hebei University of Engineering, No. 19 Taiji Load, Handan 056038,

People's Republic of China

Email: duhaiyangdhy@126.com

Introduction

A kind of smart actuator was proposed by integrating shape memory polymer (SMP) and rubber materials, in which the rubber material was placed at the middle position between two piece of SMP

plates. some pre-tension deforming was carried out on the SMP/rubber composite actuator and the

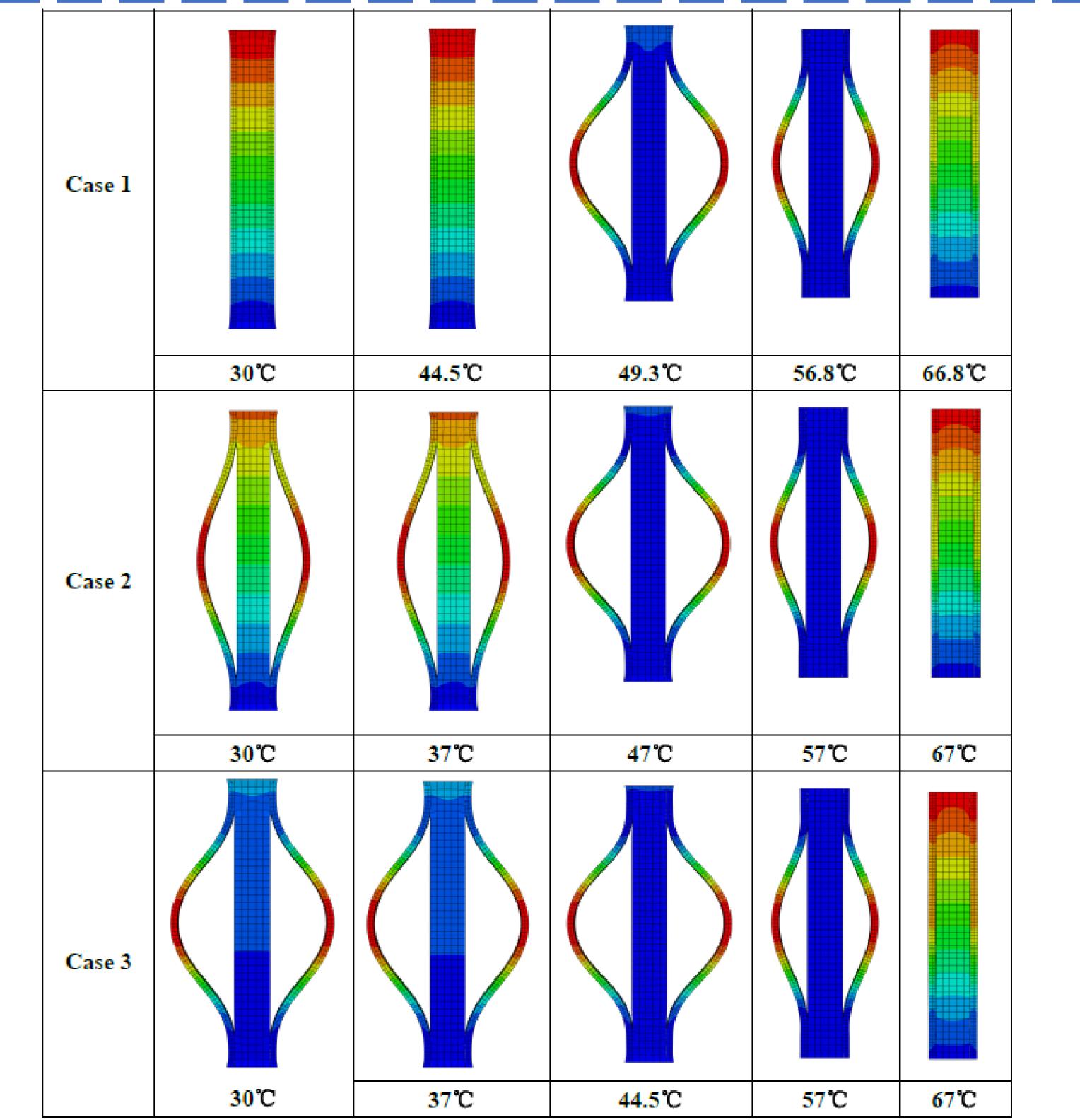
two-way shape memory effect (SME) was demonstrated during the shape recovery step.

Methods

Simulation: The Generalized Maxwell model and WLF equation shown in reference [1, 2] was applied to simulate the two-way SME during the shape recovery step with heating rate 5°C/min.

Experiment: A rubber strip (length 100mm * width 10mm * thickness 10mm) was integrating with SMP plate (length 100mm * width 10mm * thickness 1mm) to form the composite actuator.

Critical load F_{cr} for three cases : The compression load

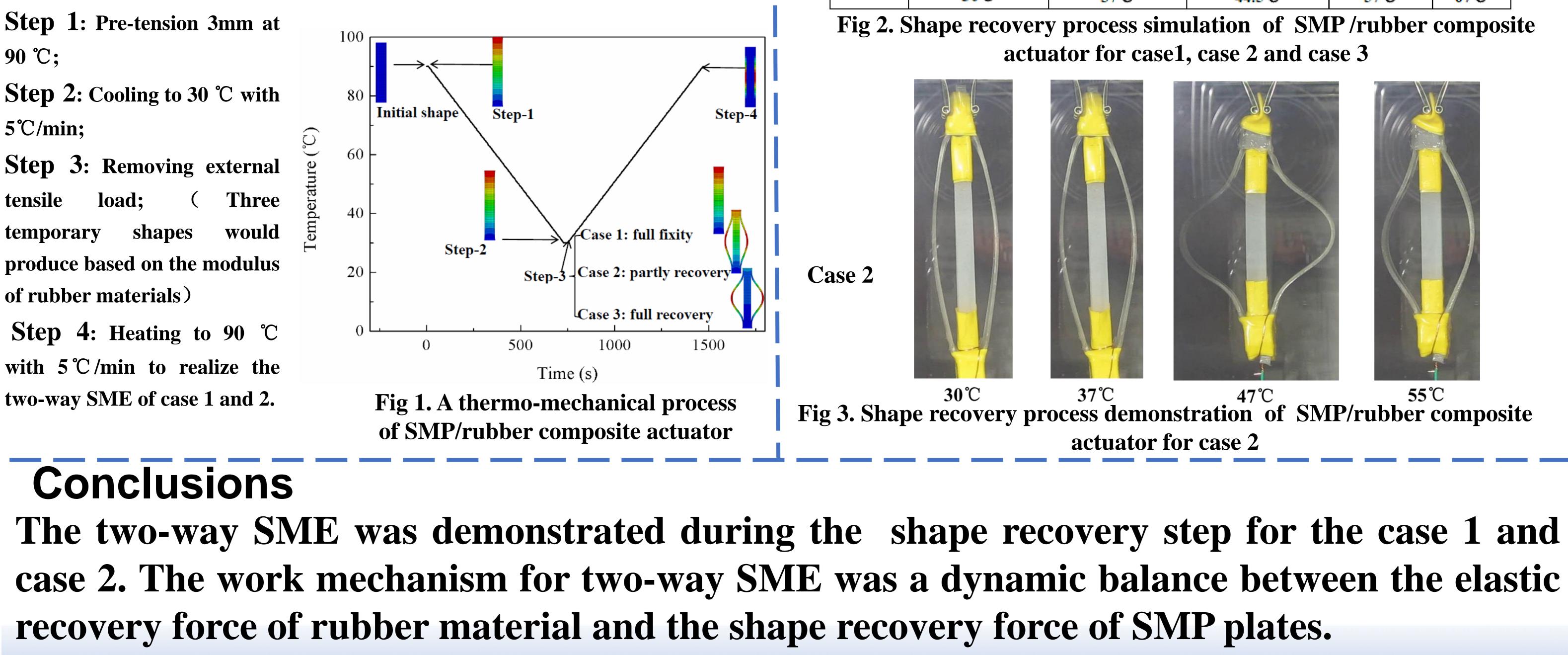


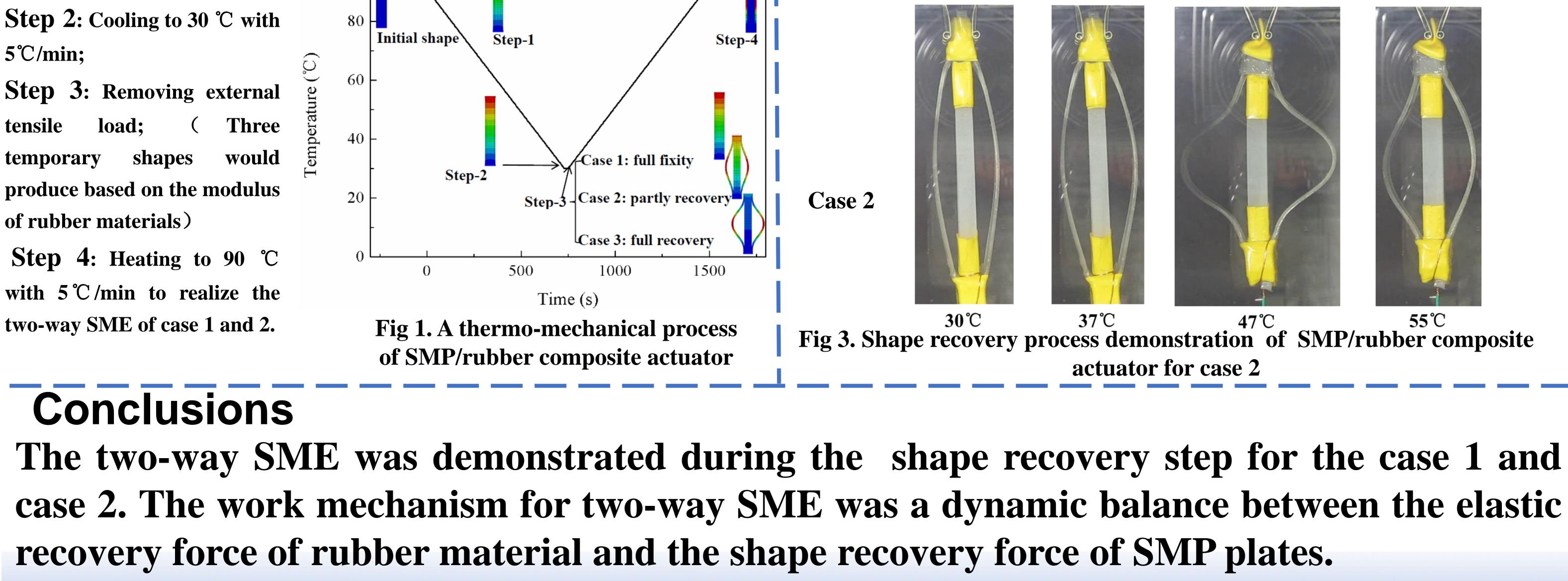
for SMP plates would be produced when temperature was cooled to 30°C for composite actuator with some pre-tension deforming. When the compression load was lower than critical load, the case 1 (full fixity) would produce.

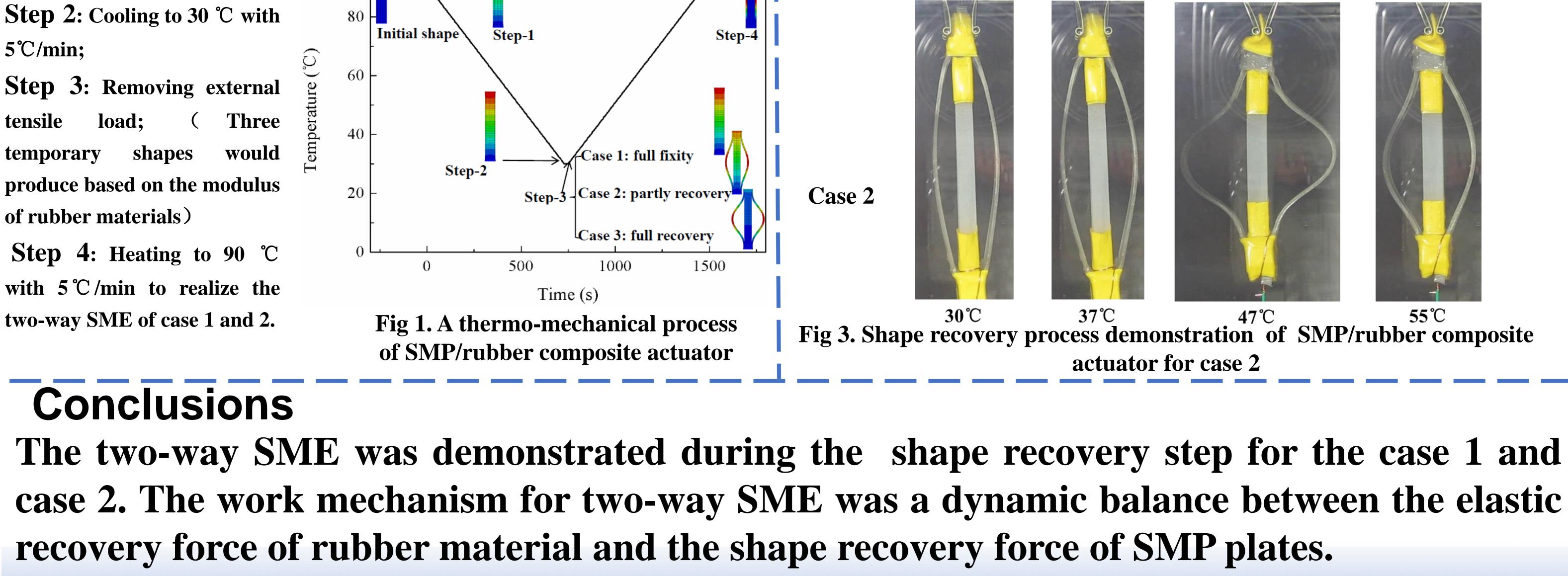
 $F_{cr} = \frac{\pi_2 EI}{\left(\mu L\right)^2}$

Discussion/Results

Step 1: Pre-tension 3mm at 90°C; **Step 2:** Cooling to 30 °C with 5℃/min; **Step 3:** Removing external Three tensile load; would shapes temporary produce based on the modulus of rubber materials)







[1] Diani J, Gilormini P, Fredy C and Rousseau I. International Journal of Solid and Structures, 2012, 49: 793-799.

[2] HY Du, LW Liu, FH Zhang, JS Leng and YJ Liu. Composites Part B: 2019, 172: 106905.